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# Developments on the interpretation and assimilation of GPSRO data at Environment Canada

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**IROWG-2**  
**Estes Park, Mar 28<sup>th</sup>, 2012**



# Outline

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- Considerations around unbiased observations
- Realization of GPSRO as a calibrated source
  - Quality of our knowledge
  - Air compressibility
  - Expression of refractivity
- Exploration of calibration's forecast value
  - Direct value
  - Indirect value through radiance bias correction

# The Numerical Weather Prediction (NWP) Objective

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- To track the atmosphere numerically:
  - Atmospheric field (AF, external)
  - Numerical field (NF, we control it)
- Tools
  - Correction of the numerical field (= **assimilation** of measurements)
  - Time propagator of the numerical field (= **forecast** model)
- Therefore:
  - We have established a link **AF**→**NF**
    - Actually (AF → Obs → NF)
  - We want this link to be as **strong** as possible

# 2 kinds of Observations

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## Absolute:

- We can state the accuracy of their calibration with high degree of confidence (more than our system)
  - Eg. Radiosondes, GPSRO, some aircraft and surface data
  - We tell the **system to trust the observations (Obs → NF)**
  - Strengthens coupling (**AF → Obs → NF**)

## Relative:

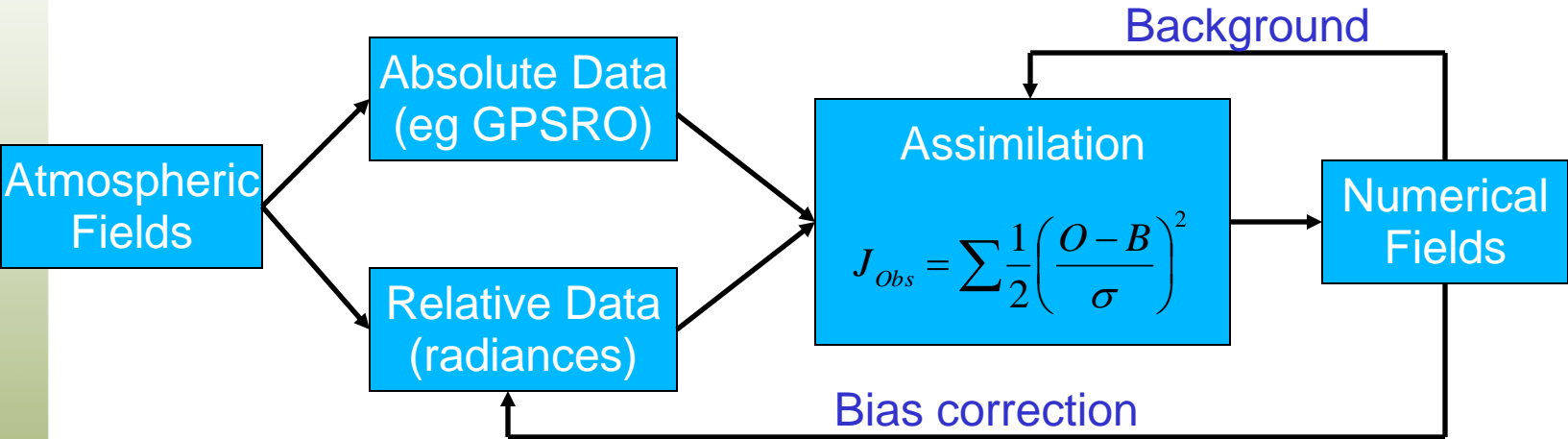
- The calibration is less known (less than our system)
  - Notably, radiances (vast amount of data)
  - We establish a bias-correction procedure.
  - We tell **observations to trust the system (NF → Obs)**

## Then:

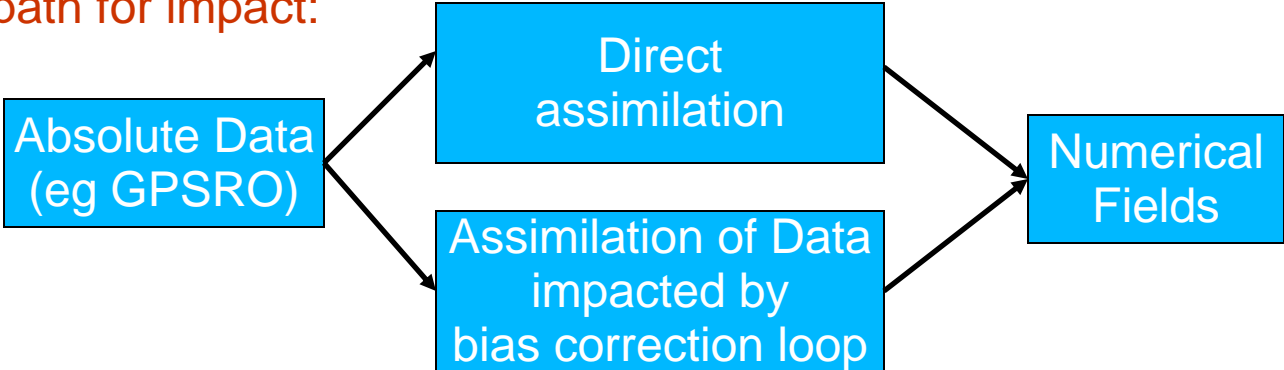
- Radiances and numerical field end **strongly coupled**
  - Bidirectional coupling (**Obs → NF**) and (**NF → Obs**)
- But actual objective (Numerical Field and Atmosphere) more **weakly coupled**
  - Coupled by **physics** and **absolute observations**



# Information flow from data



Double path for impact:



# Absolute observations

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Impact the numerical field directly

- **numerical field should trust absolute observations**
- (AF → **absObs** → NF)

Also impact indirectly:

- **relative observations should trust the field**
- (AF → **absObs** → NF → **relObs** → NF)
- Feedback loop

Then

- Absolute observations have
  - Larger **impact**
  - Higher **responsibility**

# The tolerance to bias (in NWP) : 1

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Standard view within the GPSRO community:

- “GPSRO is self-calibrating, unbiased”

But:

- 1: Is it true?
- 2: Is it verifiable?
- 3: Does it require a careful procedure? (to realize the accuracy)

Most measurements in NWP (radiances) are more biased (10x-100x)

- But nobody is claiming that they are not
- They don't receive the responsibility to calibrate other data

# The tolerance to bias (in NWP) : 2

- From an NWP user perspective, the no-bias claim means:
  - “Sufficiently unbiased to avoid degrading forecast performance”
- Window of optimum forecast quality is very narrow
  - Verified in different ways at EC, ECMWF, NCEP.
  - Width of this window about 0.05%  $(O-B)/B$
- Not so surprising:
  - GPSRO injects information at fractional levels around 0.5%  $(O-B)/B$ , leaving little room to accept a bias

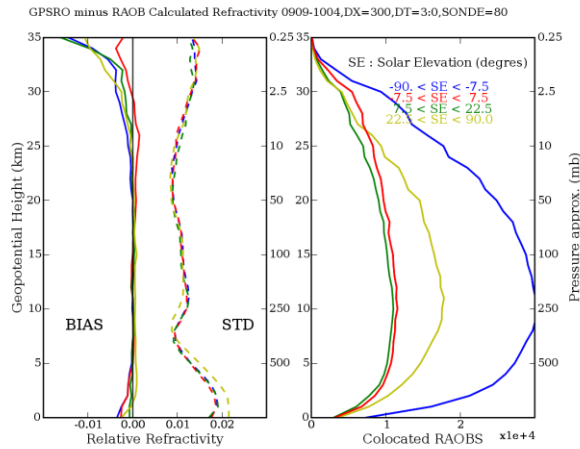




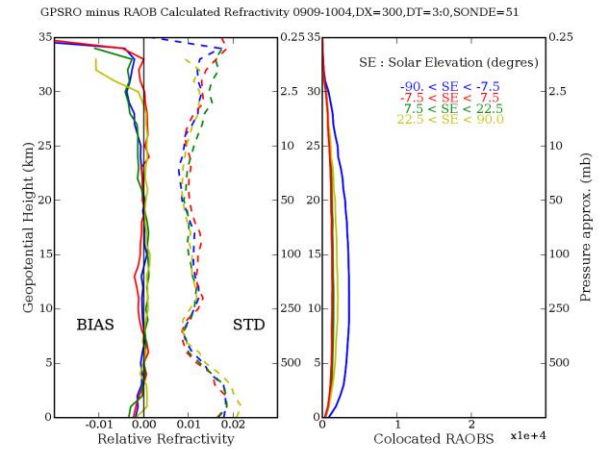
# Agreement of several « anchors »

Coincident ( $>10^4$ ) GPSRO vs several RS types, at several sun elevations

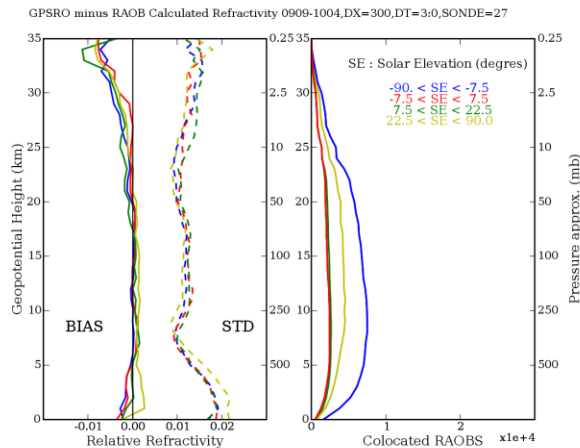
Vaisala RS92



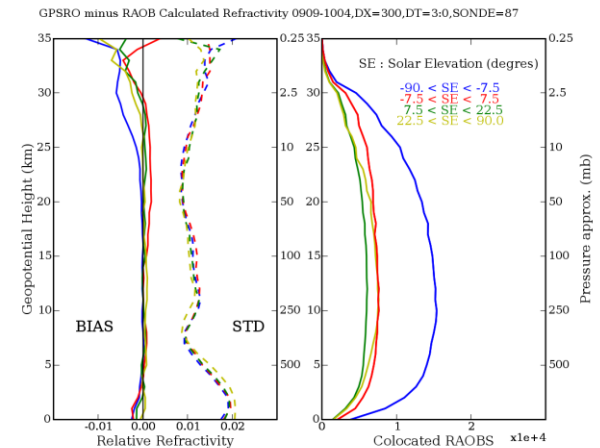
VIZ-B2



AVK-MRZ



Sippican Mark IIA



# The Refractivity-Atmosphere link

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- Measurement is  $N(\vec{x})$ 
  - Or equivalent  $N(h)$ ,  $\alpha(a)$  or other
- Interpreted as field of  $(P, T, q)$
- Required
  - Refractivity expression  $N \leftrightarrow (P, T, q)$   
Local relationship (thermodynamic)
  - Structure of the atmosphere  $\vec{x} \leftrightarrow (P, T, q)$   
Nonlocal (hydrostatic eqn, etc)

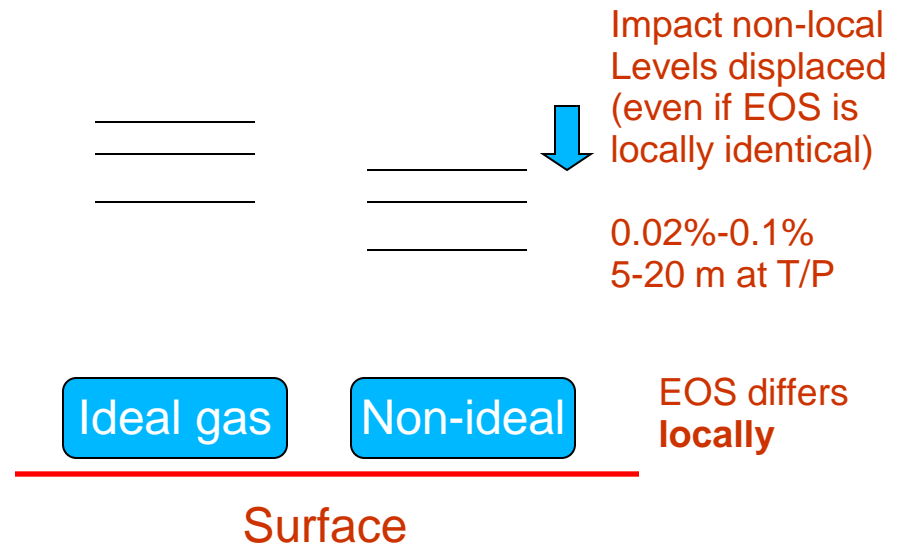
Note: NWP Obs operators must include **both relationships**

# 1: Structure of the atmosphere

- Essentially, the hydrostatic equation
- We need there the equation of state (EOS)
- Already found that the deviation of EOS from ideal is non-negligible
- **Non-local**
- 0.05% relevant for NWP if **systematic** (affects the anchor of radiances)

$$\nabla P = -\vec{g}(\vec{x})\rho$$

$$P(\rho, T, x_w)$$



## 2: Refractivity expression

- Local  $N(P,T,x)$
- Band of expressions within 0.1%
  - We already know that systematic biases of [0.01%-0.1%] do not simply translate to small fcst bias but **affect fcst precision**  
(long term accuracy, tested with GPSRO by EC, ECMWF, NCEP)

Suspected (ECMWF, NCEP) that the classical expression

requires recalibration

$$N = k_1 P_d / T + k_2 P_w / T + k_3 P_w / T^2$$

- We undertook this recalibration with
  - Theoretical modeling (microscopic/macroscopic relationships)
  - Selection of high precision data (broad range of measurements)

# Dry air refractivity

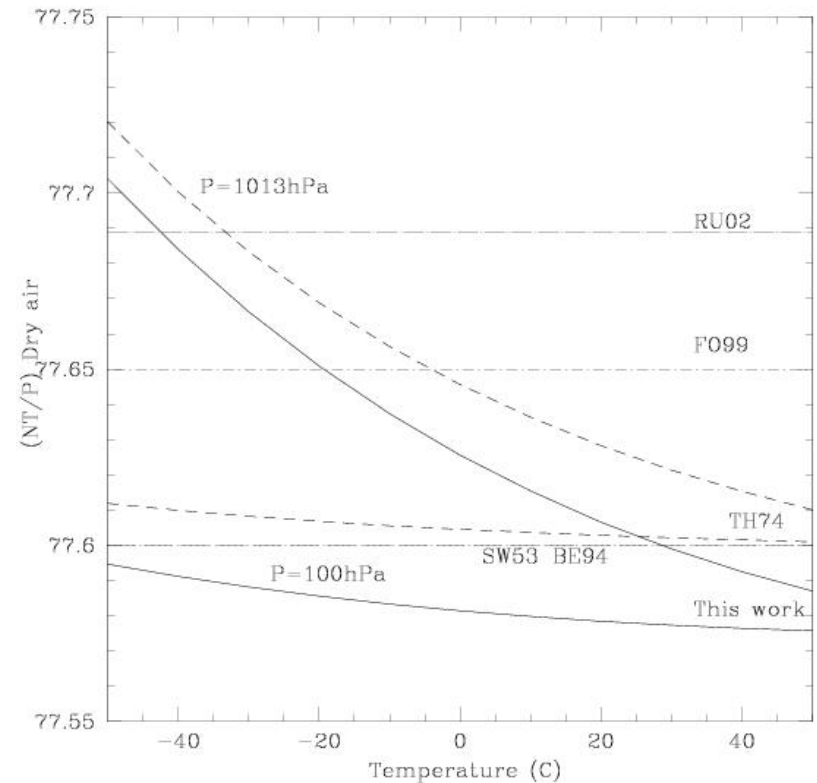
What is normally called  $k_1$   
( $NT/P$  for dry air)

Not a constant

No constant would fit to  
better than 0.1% rms  
(max err up to 0.2%)

Higher at

- low T
- high P



# WV refractivity

WV Partial pressures  
**not even well-  
 defined** in a non-ideal  
 gas

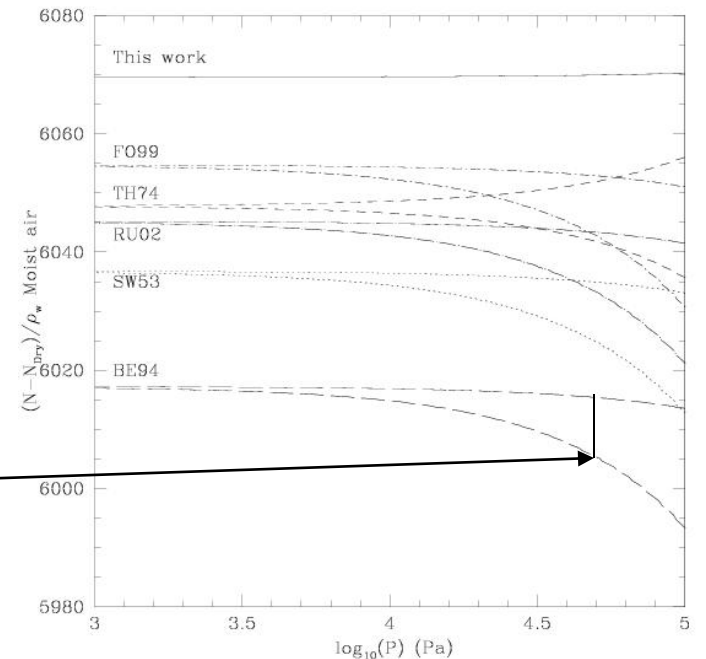
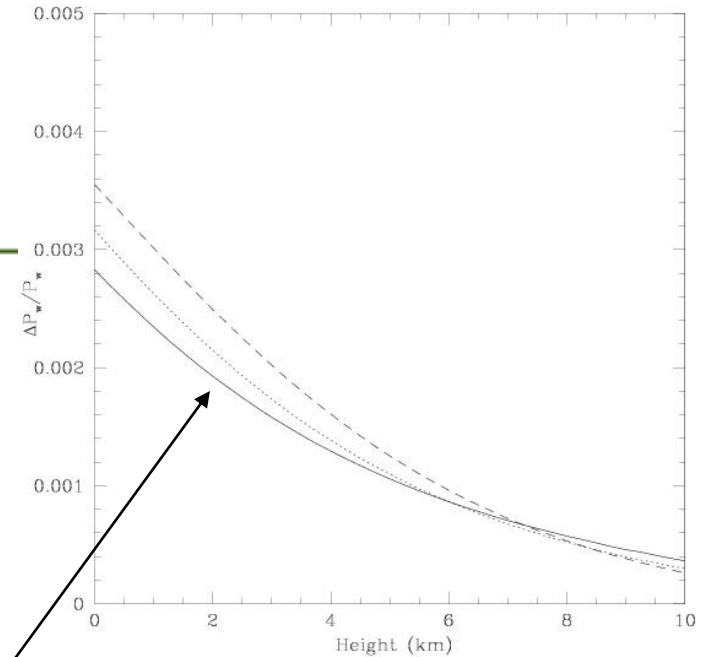
Is it:

$$P_w = x_w P$$

or

$$P_w = P - P_{dehydrated}$$

Or even another?



# Proposed setup

## Hydrostatic equation

- Should consider
- EOS should include compressibility

$$g(\lambda, h)$$

$$\rho(P, T, x_w)$$

## Refractivity expression

- Calibration should have included compressibility
- Expressions of the form

$$N = k_1 P_d / T + k_2 P_w / T + k_3 P_w / T^2$$

**cannot** attain stated accuracy (for any set of coefficients)

- By theory or experiment should consider
  - Air composition
  - Molecular polarizability
  - Electric dipoles (H2O)
  - Magnetic (O2) dipoles
  - Dielectric enhancement
  - Univocal meaning

*Proposal :*

$$N = N_0(1 + N_0 \cdot 10^{-6} / 6)$$

$$N_0 = (222.682 + 0.069 \cdot \tau) \cdot \rho_d + (6701.605 + 6385.886 \cdot \tau) \cdot \rho_w$$

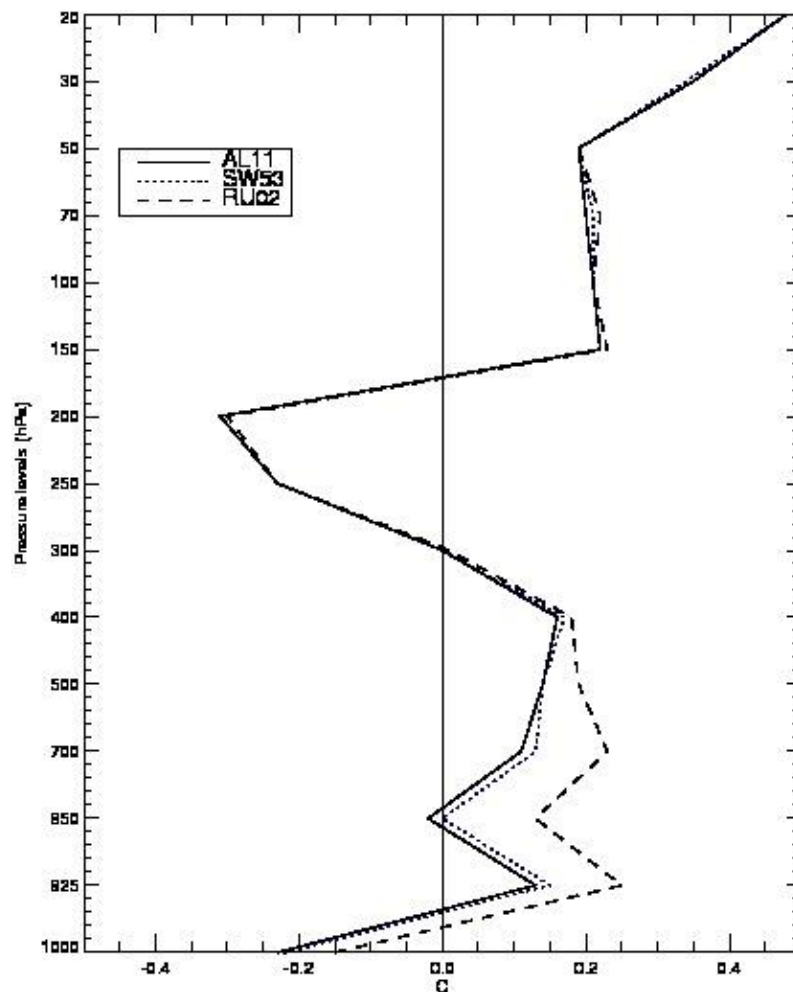
$$\tau = 273.15 / T - 1$$



# Forecast impact of the calibration I

RS Temperatures (World AVG)

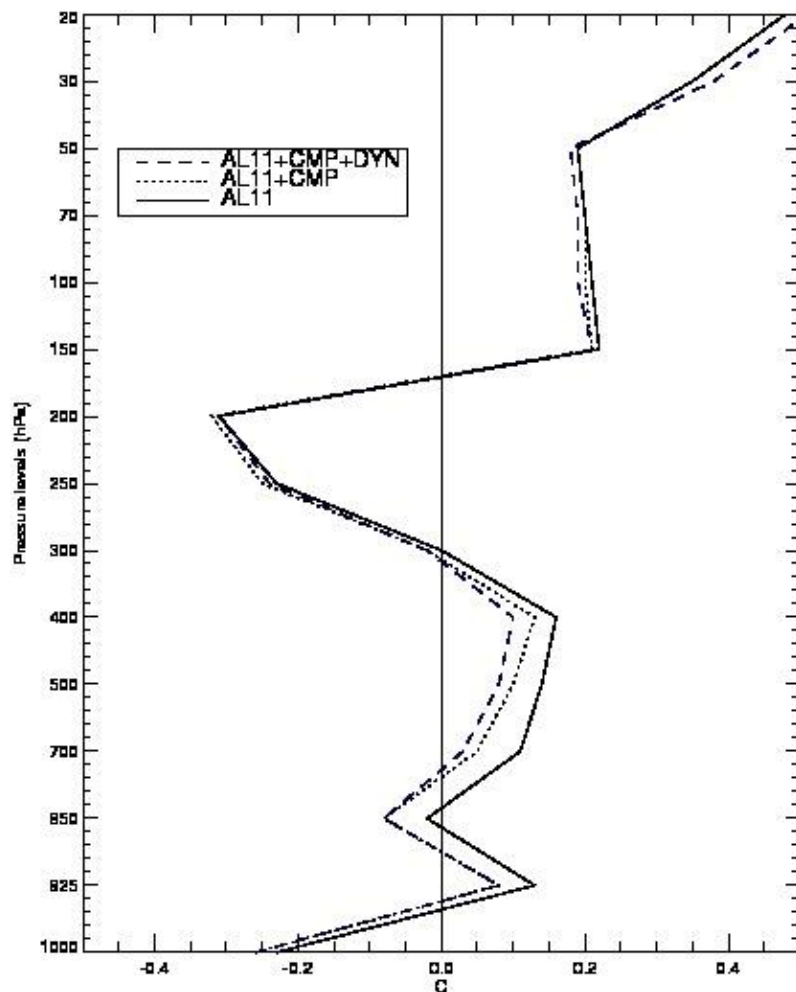
- Different implementations of GPSRO calibration
  - Our first (RU02)
  - Our refined (see former viewgraphs, AL11)
  - Other tests (SW53)
- Good tropospheric temperatures at stake



# Forecast impact of the calibration II

RS Temperatures (World AVG)

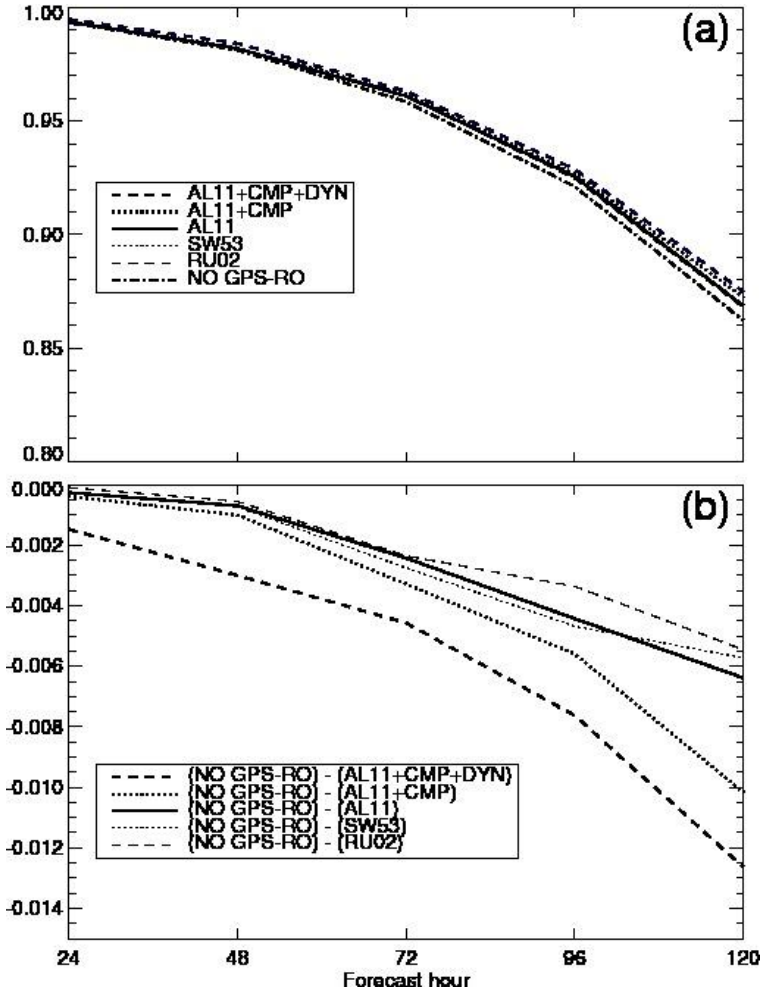
- **Bias correction**
  - Each RO implementation blocked/allowed to calibrate radiances
- Blocking/allowing (DYN) bias correction feedback loop between implementations
- Impact smaller, but comparable to differences between calibrations
- Indirect impact of RO assimilation comparable to direct impact



# Forecast impact of the calibration III

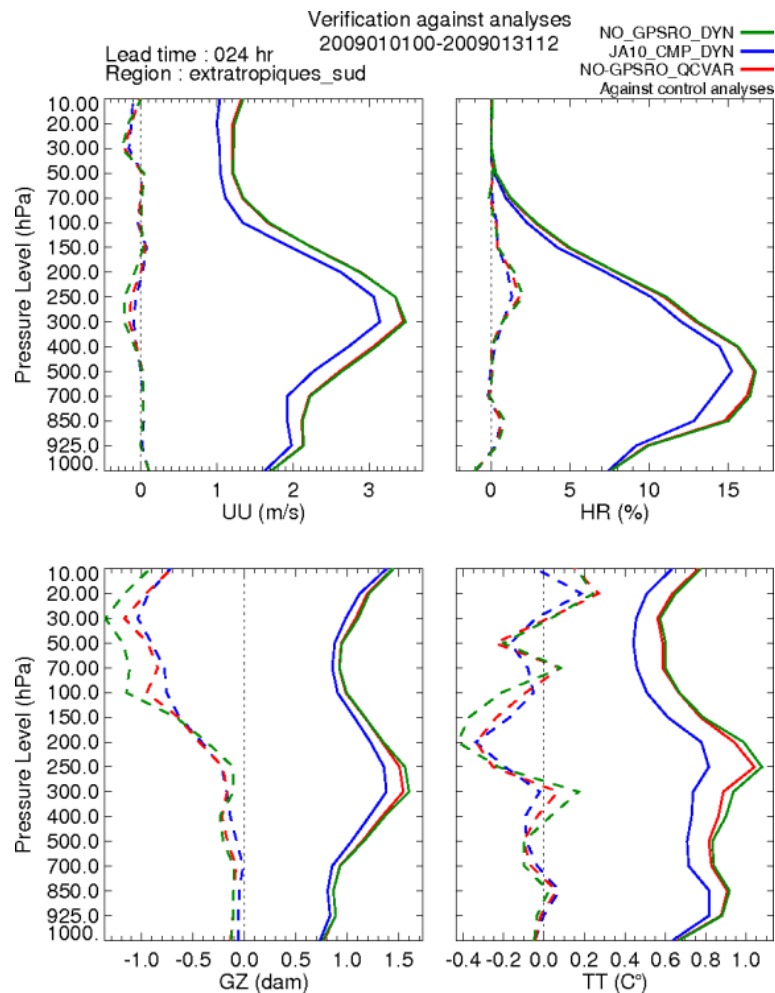
Anom CORR GZ 500

- We use NO-GPSRO as reference
- Blocking/allowing (DYN) bias correction feedback loop between implementations
- Impact comparable to differences between calibrations
- Indirect impact of RO assimilation comparable to direct impact



# GPSRO denial test

- Cycles
  - Best estimate, with its own bias correction
  - No GPSRO assimilation, but bias correction from best estimate retained
  - No GPSRO assimilation, and bias correction recalculated



# Conclusion

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- As calibrated data, GPSRO has
  - Direct impact (entered in the cost function)
  - Indirect impact (anchors radiance bias correction)
- Both impact paths have forecast value
- Different calibrations lead to different fcst performance
- Indirect impact smaller than direct, but comparable

For both reasons:

- A careful revision of intercalibration recommended for optimal results

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***Thank you!***

