

Profiling the atmosphere with the airborne RO technique using GPS signals recorded in open-loop mode

Paytsar Muradyan, Jennifer S. Haase,
Ulvi Acikoz*, James L. Garrison*, Feiqin Xie**

Department of Earth and Atmospheric Sciences, Purdue University

*Dept. of Aeronautics & Astronautics Engineering, Purdue University

** Joint Institute for Regional Earth System Science & Engineering, University of California

Aknowledgements

HIAPER UCAR Subcontract S05-39696

NSF grant SGER-0802887

Schlumberger Foundation

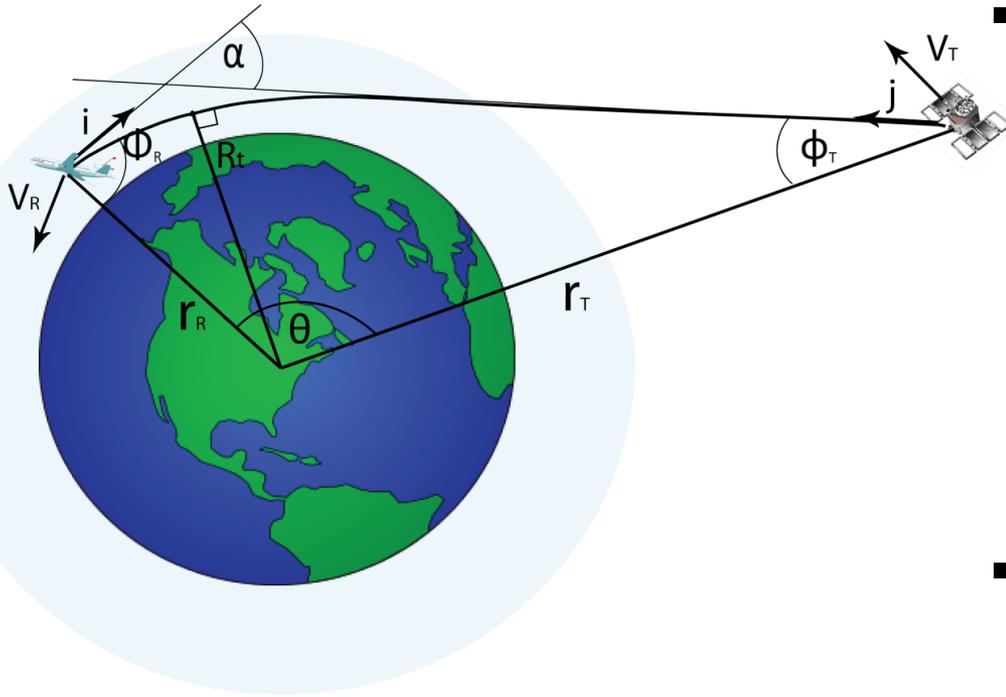
Brian Ventre, Tyler Lulich and Brian Murphy

IROWG-2

March 28-April 3, 2012

PURDUE
UNIVERSITY

Airborne Radio Occultation (RO)

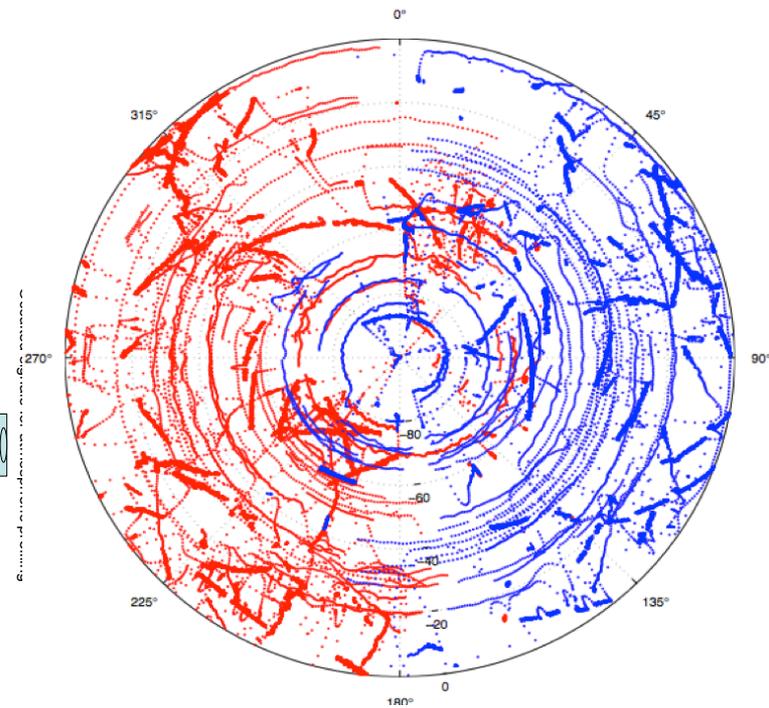
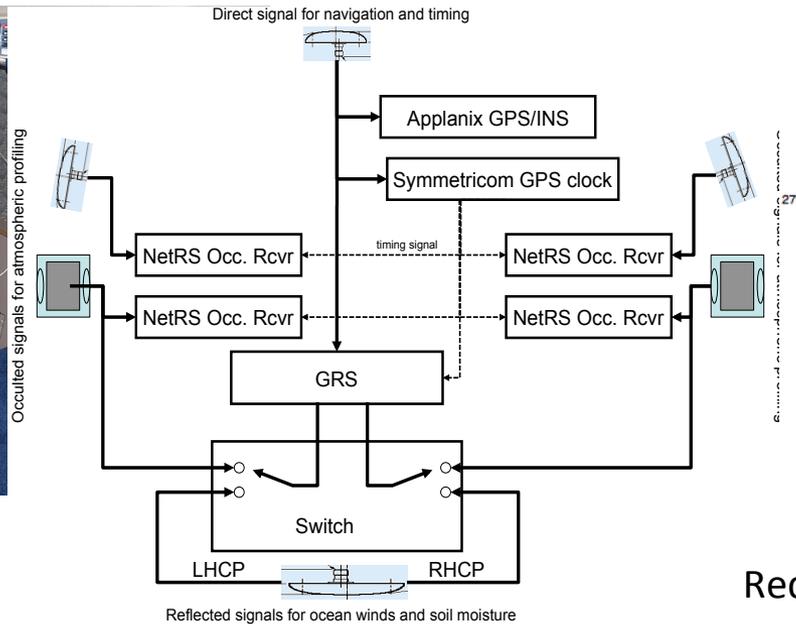


- Airborne RO measurements can contribute to understanding tropospheric moisture
 - Dense measurements of meteorological targets
 - Vertical resolution $\sim 200\text{m}$
 - Insensitive to clouds and precipitation
- Side-looking GPS antennas track setting and rising satellites
- GPS signal experiences refractive bending and delay

Problem: conventional closed loop tracking receivers have data gaps

Objective: evaluate the performance of open-loop tracking

GISMOS on HIAPER

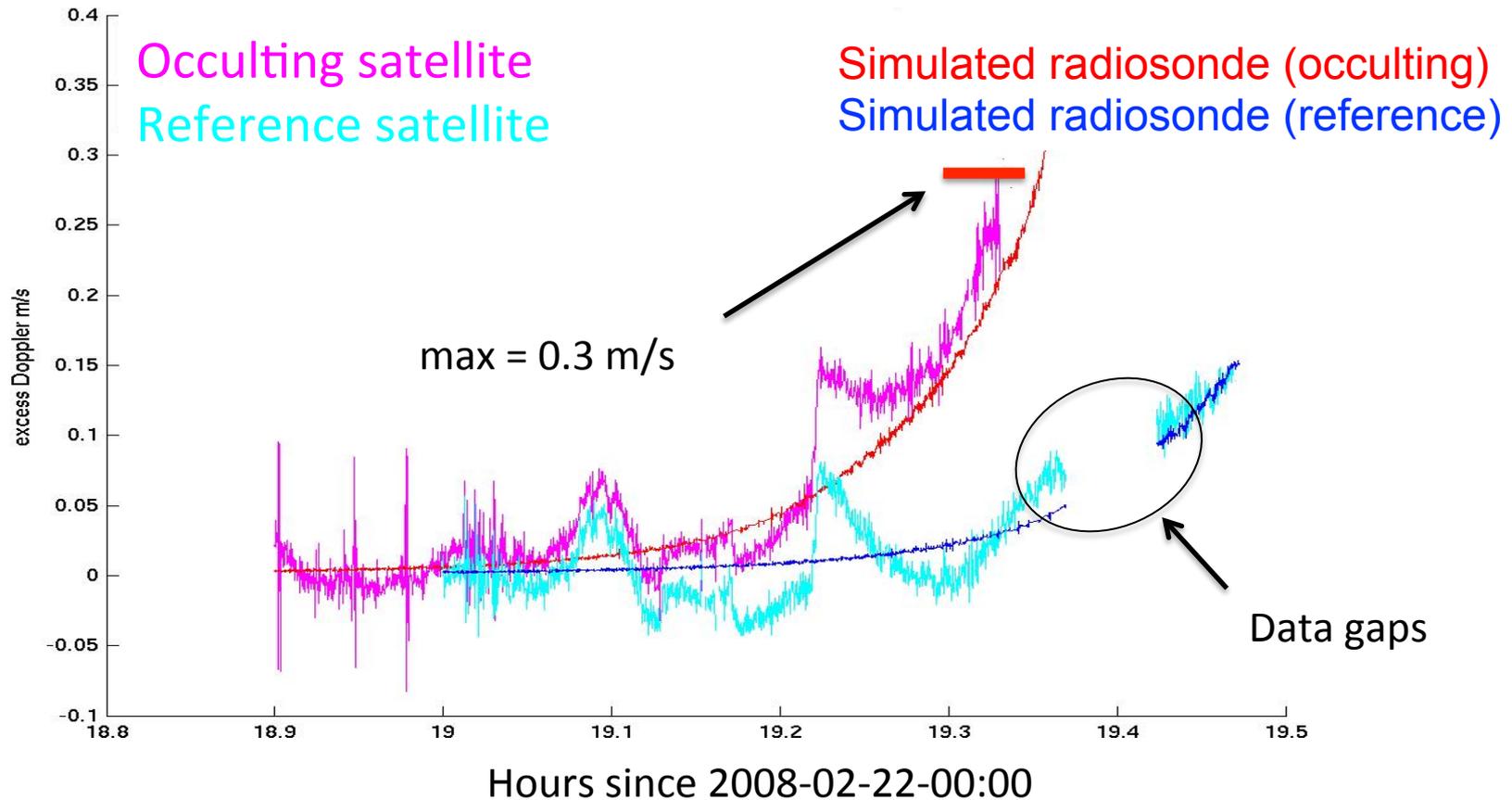


Red: Port antenna Blue: Starboard antenna

- 15.5 km maximum flight altitude
- High precision Applanix POS/AV 510 GPS/INS navigation system
- Dual-frequency geodetic quality receivers (NetRS)
- 10 MHz GNSS Recording System (GRS)
- High-gain narrow field of view antennas
- Peak Gain: 7.7 dbic L2
- 9.4 dbic L1
- Elevation: -3dB +/- 18°; -10dB +/- 30°
- Azimuth: -3dB +/- 25°; -10dB +/- 40°

Excess Doppler from NetRS Receivers

Satellite PRN12 on starboard high-gain antenna recorded with NetRS



- Limited by signal fading and multipath at low elevation angles causing the tracking loops in the conventional NetRS GPS receiver to lose lock
- Data gaps

OL Tracking of Setting and Rising Occultations

Determine the presence of signals and rough estimates of Doppler frequency



Acquisition

Generate a replica of the incoming signal.

Refine the rough estimates of code delay and Doppler from the acquisition



CL tracking

Code delay is initialized using that of obtained in CL.

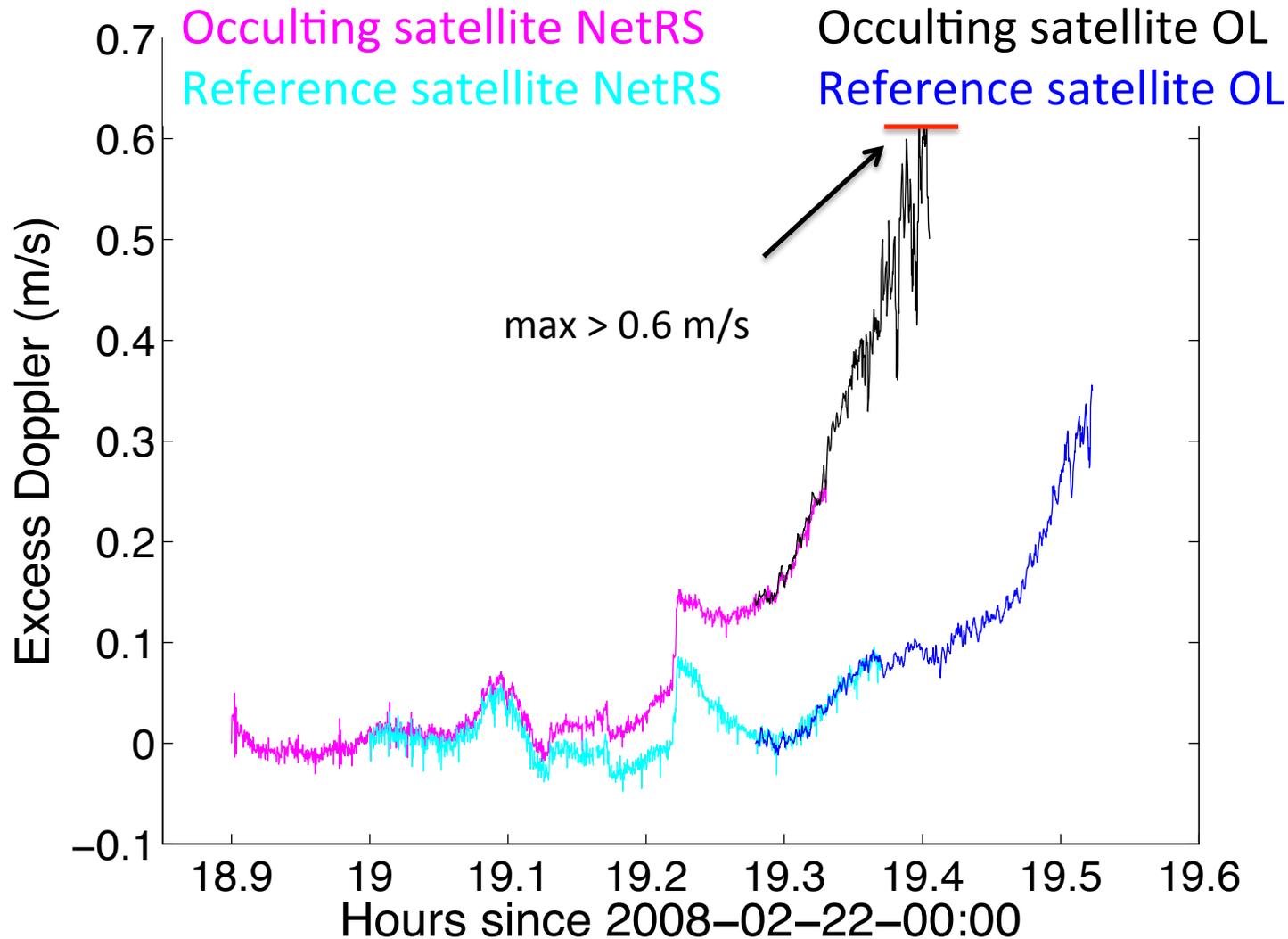
Using a geometric Doppler model, steer the phase and frequency of the locally generated replica signal



OL tracking

- Need for navigation data bits: data bits (50Hz) modulated on the I&Q phase components
- Challenge for rising occultation: signal power is low in the beginning => cannot be acquired until satellite rises to some elevation
- “Backward OL tracking” (Acikoz 2011)
 - Rising satellite is acquired and tracked with CL tracking when signal power is high enough
 - OL tracking is initialized the same way as in setting occultation case but in reverse time

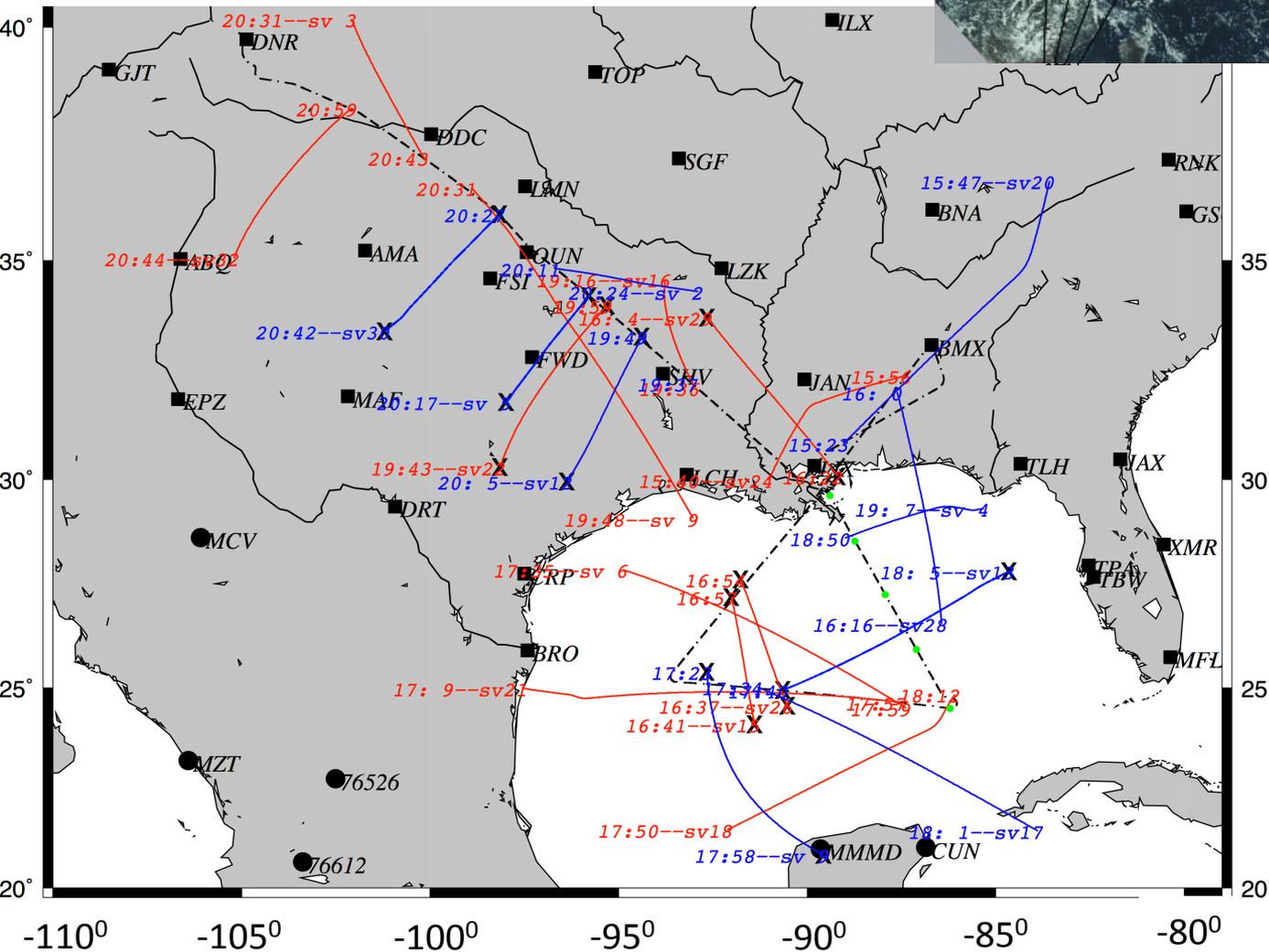
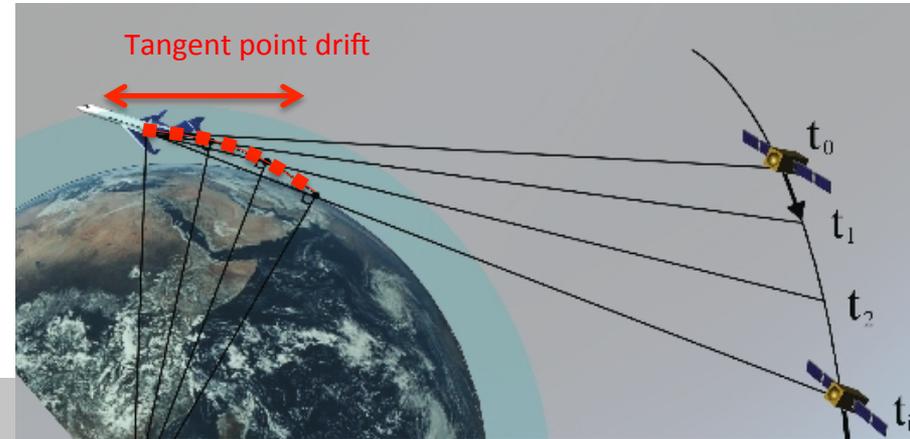
Closed-loop vs Open-loop (OL) Receiver



- Significant improvement over conventional receivers

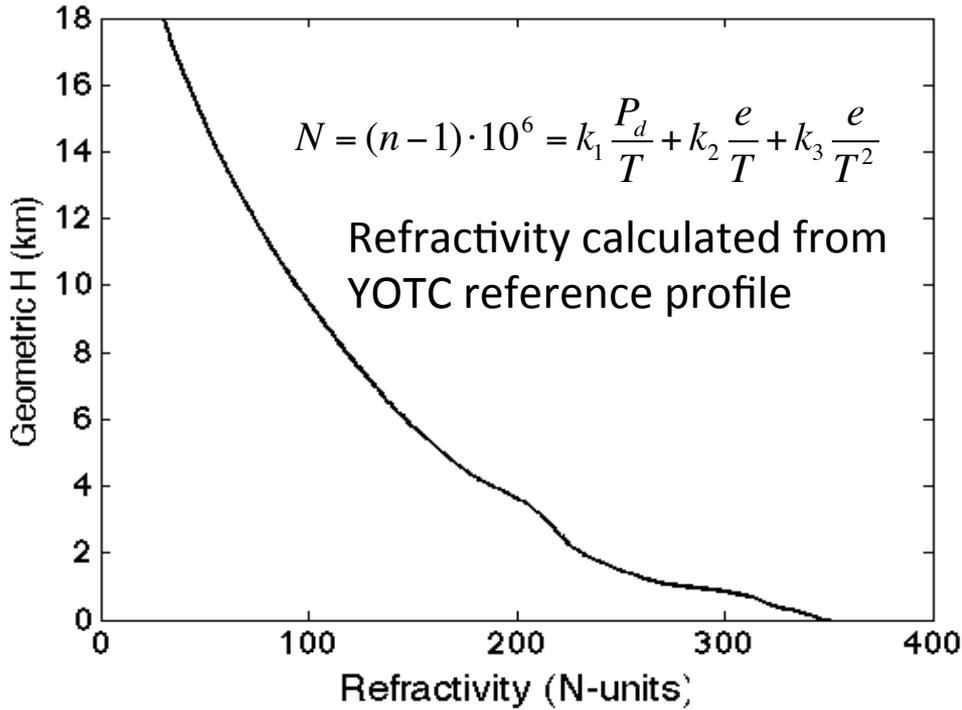
Occultation Geometry

15 FEBRUARY 2008 FLIGHT



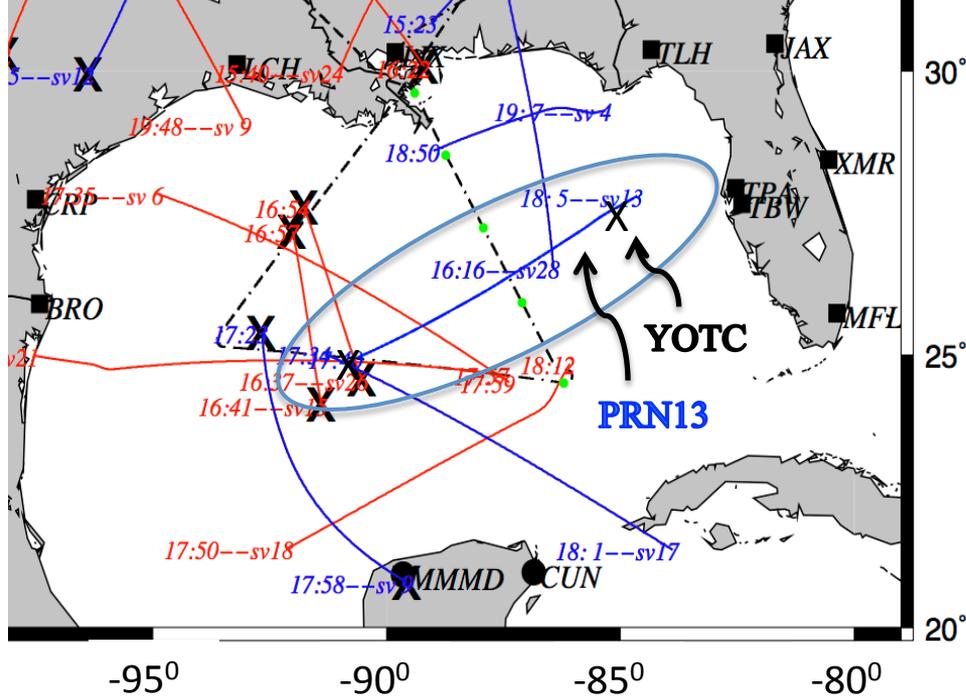
- 5 hour flight
- 13.5 km altitude
- 19 occultations when aircraft was at flight level
 - 10 setting
 - 9 rising
- COSMIC:
- 5 occultations/5 hours

YOTC profile at [27.8324 -84.6405] (G13)

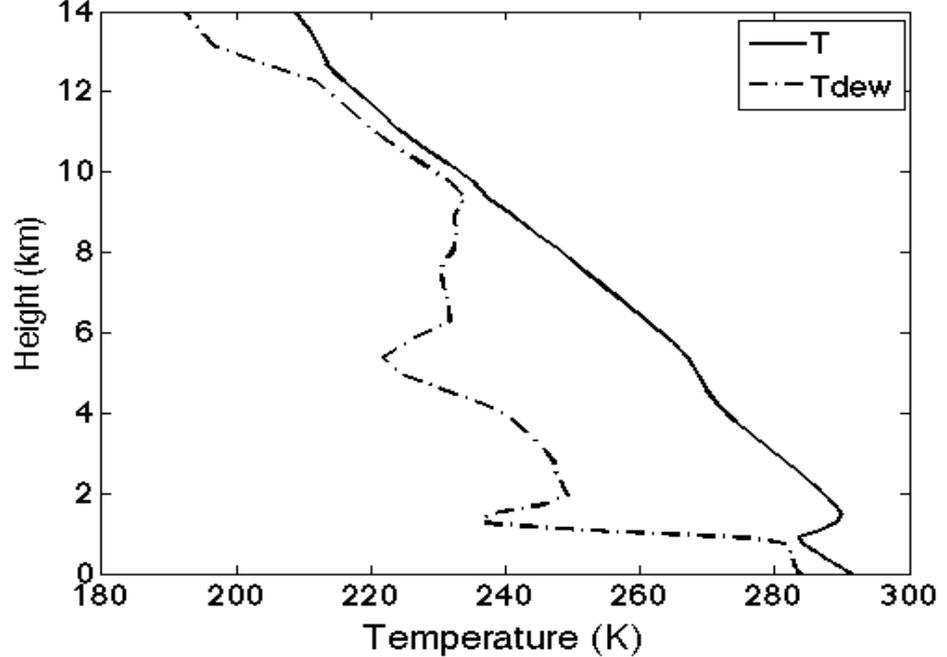


Reference profile for PRN13 is ECMWF
 -Year of Tropical Convection (YOTC)
 analysis profile at:

- ~25 km spatial resolution
- 91 levels
- Time 18:00 UTC
- Lat = [27.8324 27.7500]
- Lon = [-84.750 -84.6405]

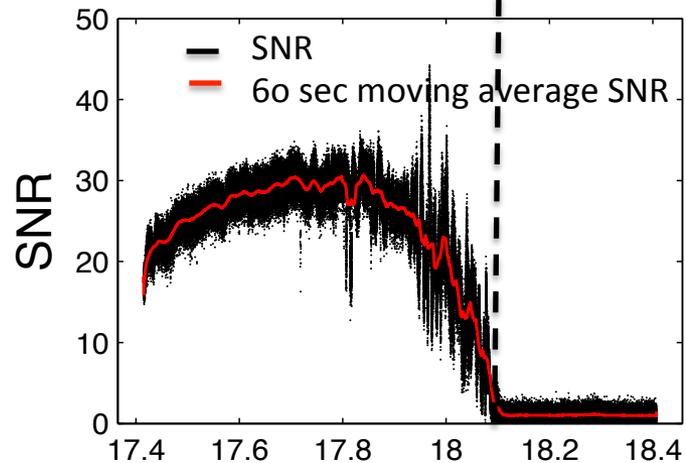
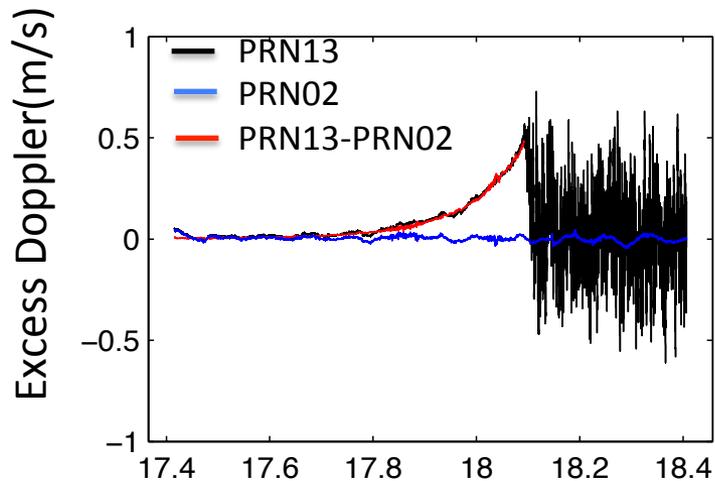
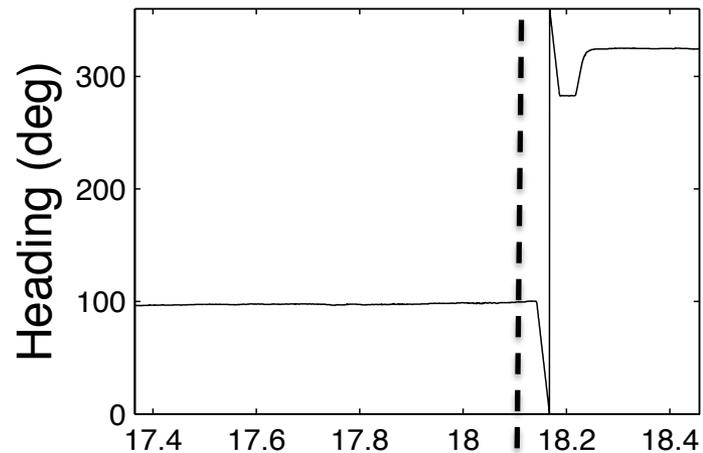
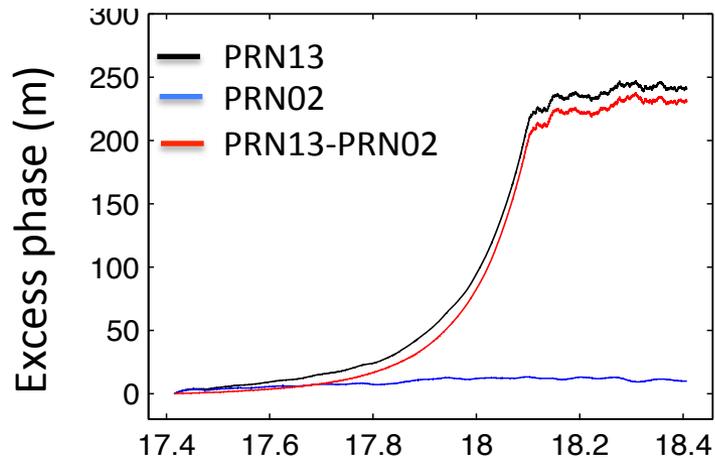


YOTC T and Tdew at [27.8324 -84.6405] (PRN13)



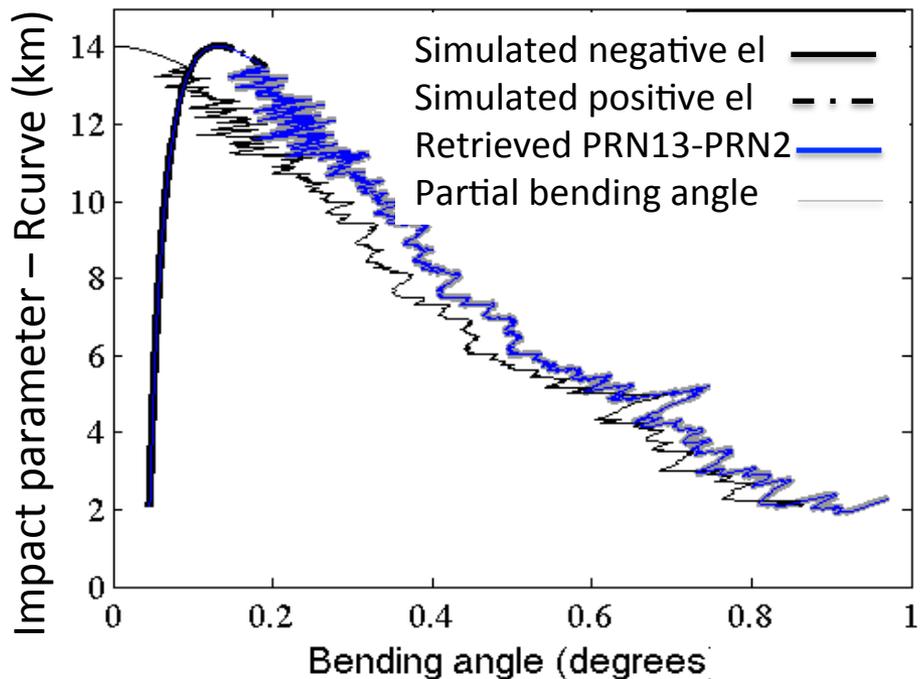
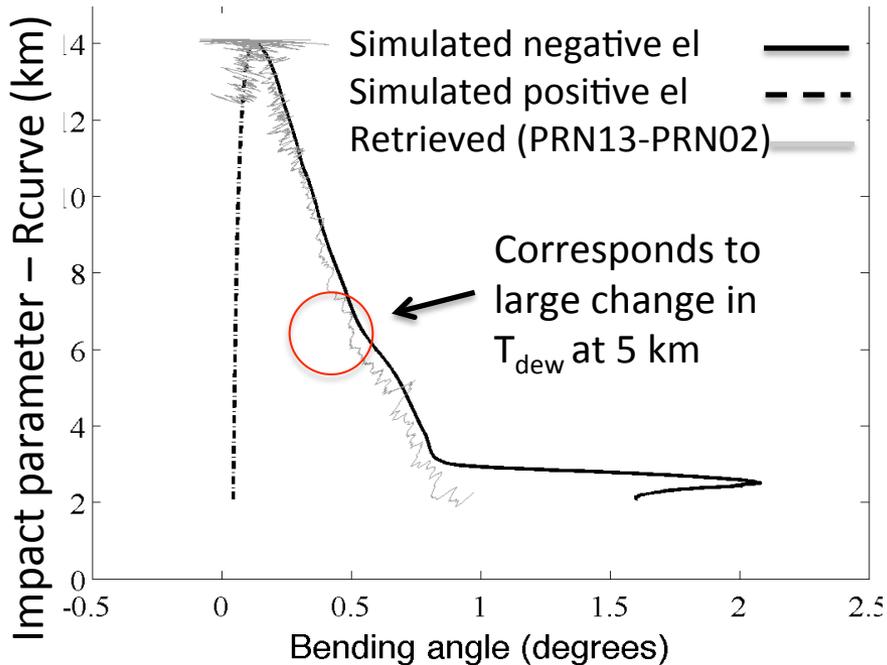
OL profiles: Setting occultation

15 February 2008 flight: Occulting GPS satellite PRN13 and high elevation satellite PRN02



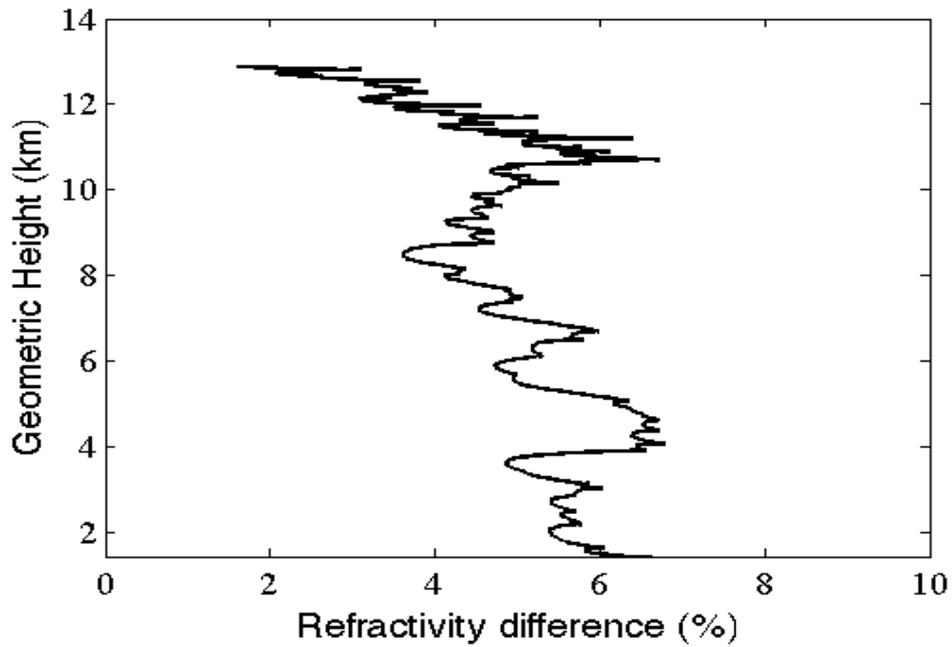
Hours since 2008-02-15-00:00

Rcurve = radius of local curvature = 6359.204 km



$$\alpha'(a) = \alpha_N(a) - \alpha_P(a) = -2a \int_{n_t R_t}^{n_r R_r} \frac{d \ln x}{dx} \frac{dx}{\sqrt{x^2 - a^2}}$$

Diff of reference and retrieved N for PRN13

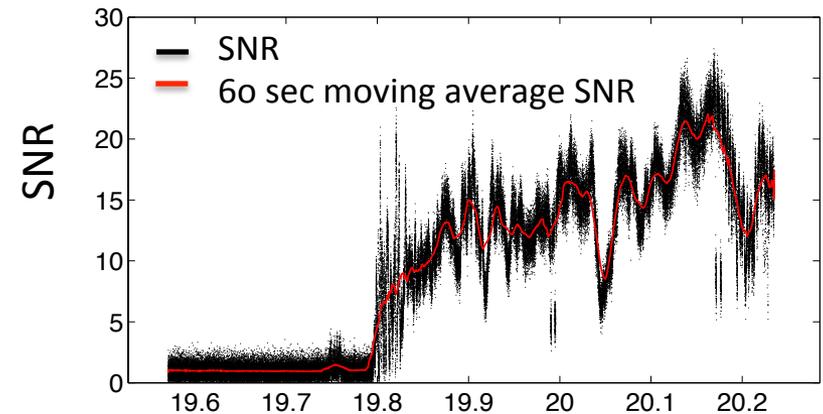
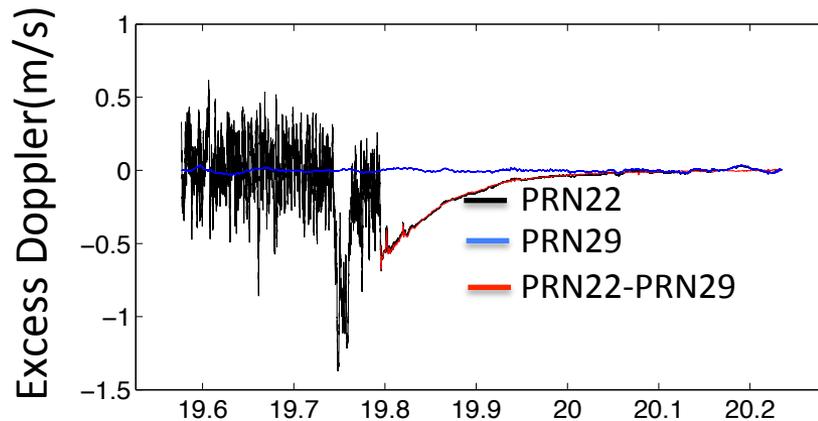
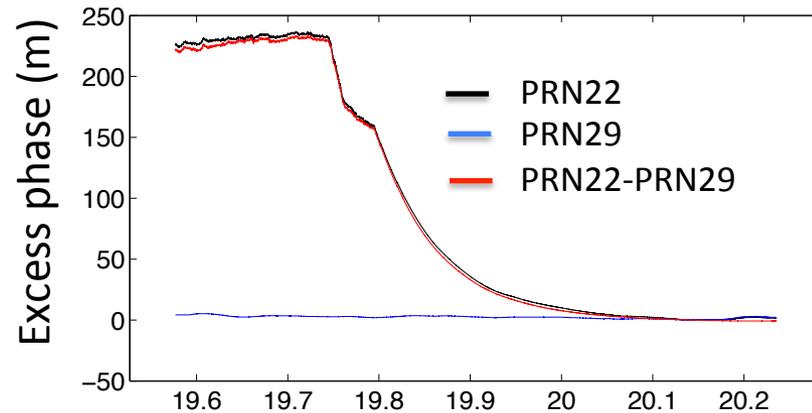


- Bias in bending angle maps into refractivity
- Bias wrt YOTC = 6% N
- Std wrt YOTC = 0.75% N from 1.5 to 11.5 km

OL profiles: Rising occultation

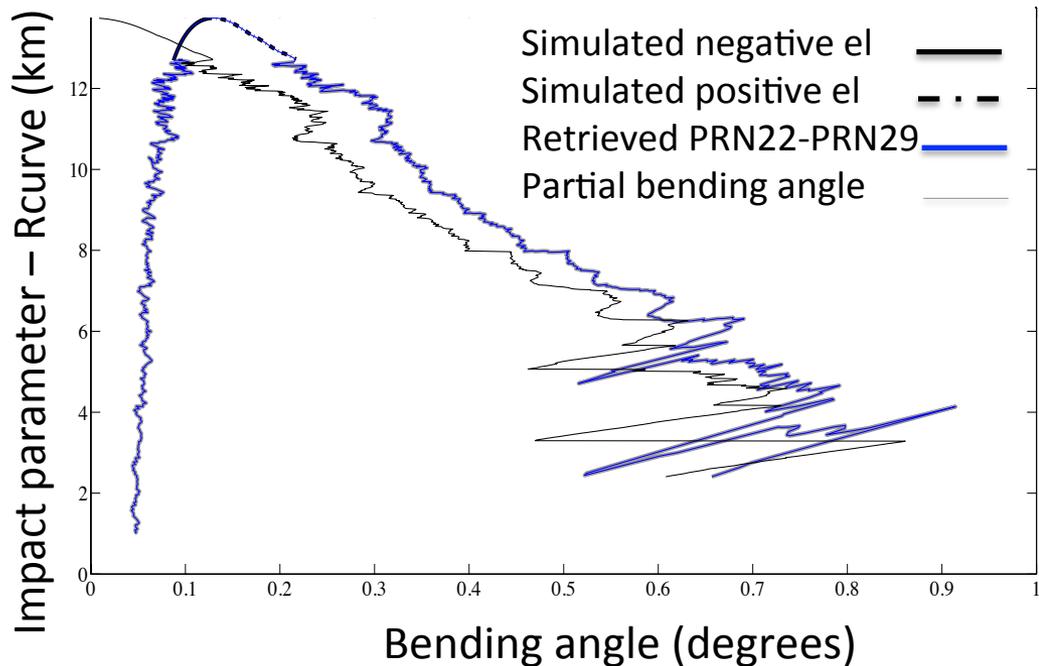
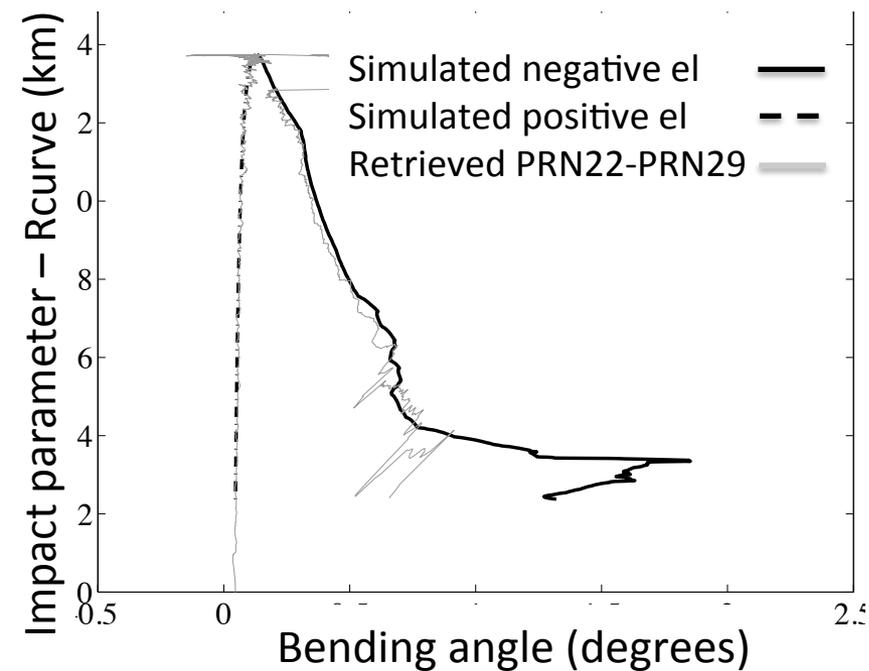
OL tracking has been implemented for rising occultations, with equivalent quality to setting occultations (Acikoz, 2011)

15 February 2008 flight: Rising GPS satellite PRN22 and high elevation satellite PRN29

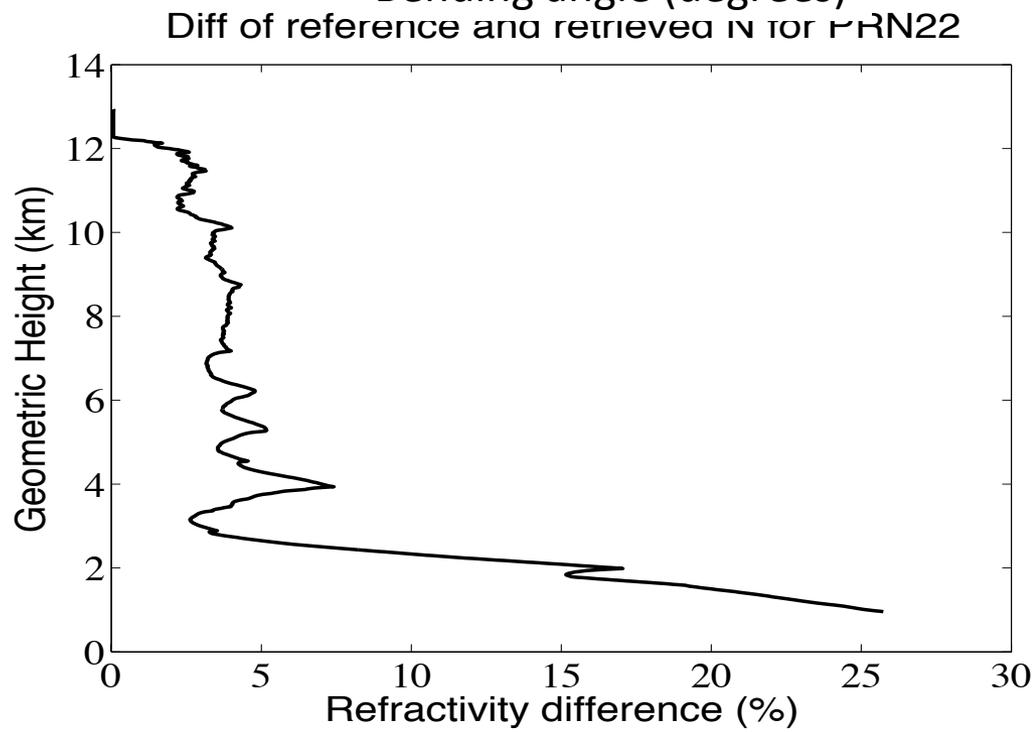


Hours since 2008-02-15-00:00

Rcurve = radius of local curvature = 6380.44 km



- Bias wrt YOTC = 5.5% N
- Std wrt YOTC = 1.5% N from 2.6 km to 13.5 km flight altitude



Summary for 9 occultations

PRN	Setting/ Rising	Port/ Starboard	Lowest Elevation (deg)	Lowest Geometric height (km)
05*	Setting	Port	-3.83	2.974
09	Setting	Starboard	-4.37	1.044
12	Setting	Port	-3.98	2.353
15	Rising	Port	-3.78	3.386
13	Setting	Port	-4.44	0.562
22	Rising	Port	-4.06	0.956
26	Rising	Port	-4.19	0.952
29	Rising	Starboard	-4.41	0.612
30	Setting	Port	-4.46	0.869

* Airplane turn truncated the profile early

COSMIC: 5 occultations/5 hrs

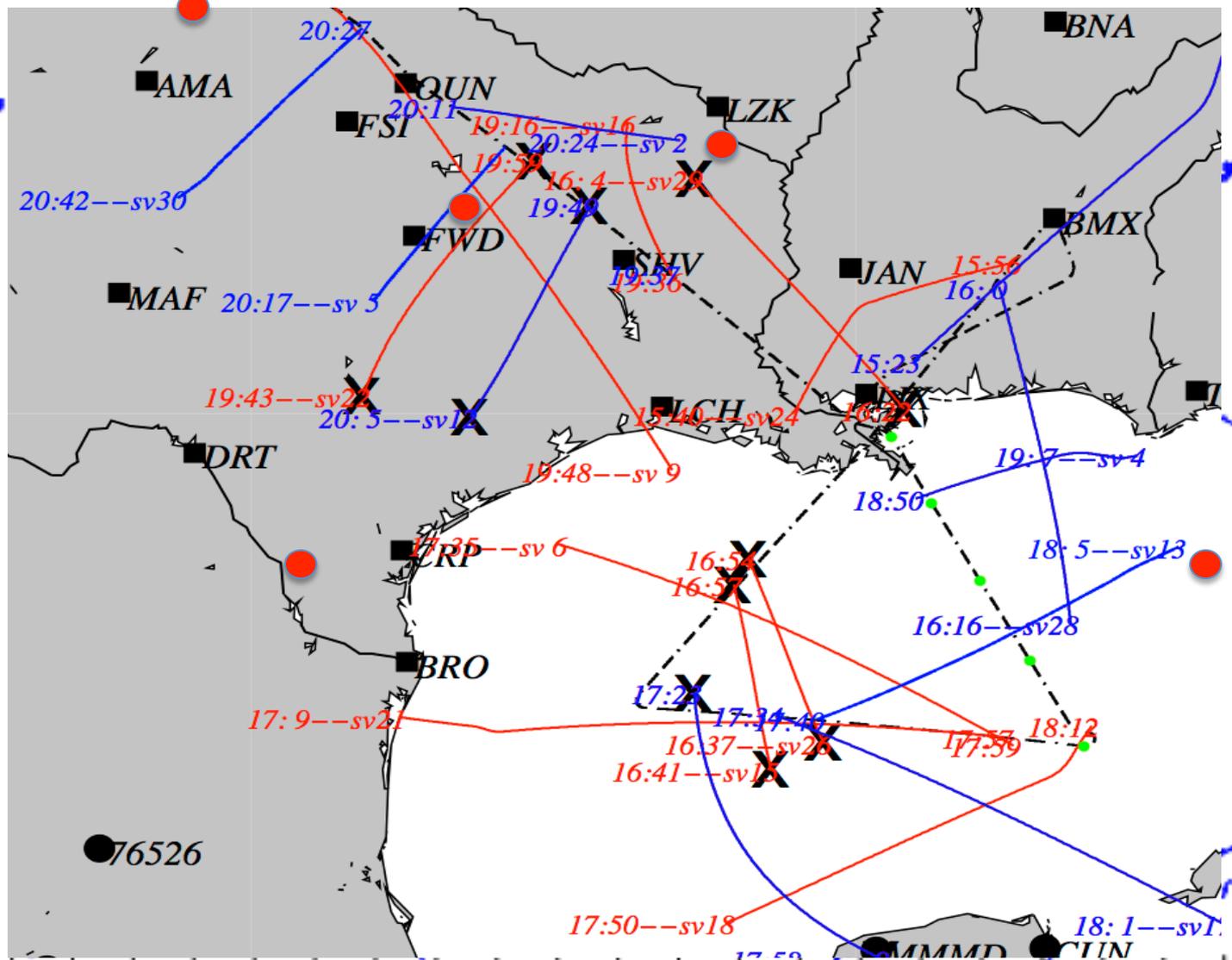
Airborne: 9 of 19 occultations/5 hrs

cosmic_occt_atmprf.latn (deg North)

35

30

25



-105

-100

-95

-90

-85

cosmic_occt_atmprf.lonn (deg East)

Number predicted \neq observed

Most important factors for missed occultations:

- Lack or poor quality of navigation data bits
 - 5 out of 19 occultations
 - Current global coverage is 99% (F. Zus 2011)
- Aircraft turns
 - 3 out of 19 occultations
- One occulting satellite was not acquired in CL tracking, which is required to align navigation data bits to initialize OL tracking
- One occultation was missed since GRS recording was stopped during the occultation

Conclusions

- Quality or absence of navigation data bits and the aircraft turns were the most important factors affecting the number of airborne RO profiles
- With an improved global network providing data bits, 2.8 occultations per hour can be achieved on a straight flight, majority to 1 km height, rising and setting.
- The retrieved refractivity profiles currently have a $\sim 6\%$ N bias and $\leq 1.5\%$ STD relative to ECMWF YOTC reanalysis
- Fourier Spectral Inversion will be needed to improve results
(F. Xie IROWG-2 poster presentation)
- B. Murphy will present results from the 2010 PREDICT campaign for investigating the initiation of tropical cyclones at the AMS conference on Hurricanes and Tropical Meteorology in April

