Preliminary results of ionosphere measurement from GNOS on China FY-3C satellite

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Outline

- Introduction to FY-3C & GNOS
- GNOS ionospheric measurement results
- Summary and outlook



Introduction to FY-3C





- FY (FengYun): Chinese meteorological satellite
- FY-3: second generation polar-orbiting satellite
- FY-3C: 3rd flight unit of the FY-3 series ; First satellite of the FY3 02 batches
- Operational satellite

Orbit	Sun-synchronous orbit
Altitude	836 km
ECT	10:15 desc
Launch	2013-09-23
End of life	≥2018
Status	Operational



Introduction to GNOS ON FY-3C





- GNSS occultation sounder
- GNOS Measures the phase delay due to refraction during occultation between GNSS satellites and FY-3C
- GNOS receives signals from GPS and BDS

Parameter	Content		
Constellation	GPS:L1、L2 BDS:B1、B2		
Channel number	Positioning: 8 Occultation: GPS 6 BDS 4		
Sampling rate	Ionosphere occultation: 1Hz		
Designed Precision of F2 peak electron density	20%		



■ L1

- ✤ Ionosphere excess phase (IE)
- nc format

■ L2

- Electron density profile (EDP)
- nc format



Present status























Data

- GNOS EDPs
 - GPSRO:2013.272----2014.247
 - BDSRO:2013.274----2014.090
- Ionosonde observation data
 - Source: GIRO(Global Ionospheric Radio Observatory)
 - 54 sites

Compared Parameters

- ♦ NmF2 (foF2→NmF2)
- ✤ hmF2







Data quality control

- GNOS EDPs quality control
 - Incomplete profiles were wiped off
 - Profiles that NmF2<0 were wiped off
- Ionosonde data quality control
 - Record that have both hmF2 and NmF2 simultaneously w as kept;

Space weather condition screening

☆ Kp < 4

Time-space matching

- Time interval < 0.5 hrs</p>
- Spherical distance < 200 kms</p>



Evaluation1: GPSRO NmF2 ——ensemble





Good agreement between the GNOS GPSRO and the ionosonde measurement



Evaluation1: GPSRO NmF2





Re.std. : rising > setting



Evaluation1: GPSRO NmF2





Re.std. : daytime < nighttime



Evaluation1: GPSRO NmF2





Evaluation1: GPSRO hmF2—ensemble





Also agreement



Evaluation1: GPSRO hmF2





Std. : rising < setting



Evaluation1: GPSRO hmF2





Std. : daytime < nighttime



Evaluation1: GPSRO hmF2





Evaluation1: BDSRO NmF2 ——ensemble





NmF2 Re.Std.: BDSRO > GPSRO, but slightly



Evaluation1: BDSRO hmF2 ——ensemble





hmF2 Std.: BDSRO < GPSRO, but slightly

the precision of EDP production of BDSRO is equivalent to that of GPSRO



GPSRO-IONO NmF2



Dataset	Corr.Coef.	Re.bias	Re.Std.	Number
ensemble	0.95	3.98%	16.80%	423
Rising	0.94	2.97%	18.74%	172
Setting	0.96	4.68%	15.32%	251
Daytime	0.92	2.99%	16.19%	254
nighttime	0.96	5.47%	17.60%	169
winter	0.94	0.29%	18.30%	108
Spring & autumn	0.95	5.43%	17.89%	209
Summer	0.96	4.90%	11.82%	106
Low latitude	0.87	4.22%	19.07%	60
Middle latitude	0.96	4.37%	15.83%	270
High latitude	0.94	2.72%	18.05%	93

GPSRO-IONO hmF2

Dataset	Corr.Coef.	Bias	Std.	Number
ensemble	0.84	2.32 km	27.26 km	423
Rising	0.87	2.14 km	25.97 km	172
Setting	0.81	2.45 km	28.15 km	251
Daytime	0.83	3.75 km	26.35 km	254
nighttime	0.74	0.18 km	28.51 km	169
winter	0.74	-6.08 km	34.75 km	108
Spring & autumn	0.87	5.31 km	21.55 km	209
Summer	0.87	5.00 km	27.16 km	106
Low latitude	0.93	5.88 km	20.18 km	60
Middle latitude	0.84	1.42 km	24.32 km	270
High latitude	0.48	-3.79 km	35.45 km	93





FY-3C GNOS comparison with ionosonde

- ✤ For GPS RO:
 - Corr. Coef. For NmF2 >0.9
 - Corr. Coef. For hmF2 >0.7
 - NmF2 Re.Std. <20%
 - hmF2 Std. <30km
- For BDS RO:
 - NmF2 Corr. Coef.=0.96
 - hmF2 Corr. Coef.=0.8
 - NmF2 Re.Std. =20.58%
 - hmF2 Std. =25 km

The results show good agreement between the GNOS and the ionosonde measurement, and the precision of EDP production of BDSRO is equivalent to that of GPSRO



Evaluation2: comparison with IRI







This figure gives the NmF2 maps as functions of geographic latitude and longitude from GNOS measurements (top panel) and IRI model results (bottom panel) in the Northern Hemisphere. The black line describes the location of the magnetic equator.







hmF2 maps of GNOS measurements and IRI results



Observed example: particle precipitation induced in the second se





Longitude (degree)





- In addition to GPS, GNOS is capable of tracking the B DS signals from the LEO for the first time.
- Preliminary comparisons show good agreement betw een the GNOS and the ionosonde measurement, and the precision of EDP production of BDSRO is equival ent to that of GPSRO.
- The comparison between the FY3C/GNOS data and t he IRI model is also reasonably good, but the IRI mod el tends to overestimate NmF2 at the crests of the eq uatorial anomalies.
- GNOS EDPs show ionization enhancement around E layer during nighttime due to the energetic particle pre cipitation over the Aurora and SAA regions.







More satellites to carry the GNOS onboard

- ***** FY3D
- FY3E
- ***** FY3F
- FY3G
- ✤ FY3H

More RO channels to observe ionosphere RO eve nts

♦ GPS RO channels: 6→8

♦ BDS RO channels : 4→8

More BDS satellites to track the signals

- About 40 BeiDou navigation satellites in total by 2020
- ✤ Global coverage

Promote the quantity and quality of GNOS RO data

http://satellite.cma.gov.cn/portalsite/default.aspx



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GNOS data start from June 1st,2014





THANK YOU

